

## 17th International Conference on Control, Automation, Robotics and Vision December 11 -12, 2022 Singapore



## **Finalist Paper Certificate**

Presented to

Kanwischer Alexander and Oliver Urbann

for the paper entitled

A Machine Learning Approach to Minimization of the Sim-To-Real Gap Via Precise Dynamics Modeling of a Fast Moving Robot

Kezhi Mao

General Chair

**Danwei Wang** 

**Award Chair**